Predicting Inflation with Neural Networks

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 - ▶ Big-data environment & highly nonlinear
 - Linear shrinkage methods (LASSO, adaLASSO, RR) Inoue and Kilian (2008), Medeiros and Mendes (2016)
 - Nonlinear methods (random forests, SVM, neural networks) Nakamura (2005), Sermpinis et al. (2014), Chakraborty and Joseph (2017), Medeiros et al. (2019)

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This paper

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 - ▶ Algorithm designed to model time series data
- 2. Relevance of macroeconomic data in the prediction (compared to CPI-only information)
 - ▶ Real, nominal & financial data (excluding CPI) versus CPI data
- 3. (By-product)
 - Common components
 - Sensitivity analysis of initial values

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- 1. Accuracy. Neural nets present better performance than usual benchmarks, especially at the one and two-year horizon forecasts
- 2. **Recurrent neural net.** At least as good as the traditional feed-forward neural network at medium-long horizons
- 3. Other predictors vs CPI. Macroeconomic information is important during periods of high uncertainty (Stock and Watson (2009), Medeiros et al. (2019))
- 4. No sparcity. All groups of predictors seem to be important to predict inflation (Giannone et al., 2018)

Econometric framework

Consider two sets of predictive variables for t = 1, ..., T

 $\mathbf{x_t} = (x_{1t}, ..., x_{Nt})'$: pool of economic predictors $\mathbf{y_t} = (y_{1t}, ..., y_{Mt})'$: CPI and its components

- the set $\mathbf{y_t}$ is not contained in $\mathbf{x_t}$

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 - the set $\mathbf{y_t}$ is not contained in $\mathbf{x_t}$

Let $\mathbf{z_t}$ be the set collecting the predictors at time t

- $\mathbf{z_t} = \mathbf{x_t}, \mathbf{y_t} \text{ or } (\mathbf{x_t}, \mathbf{y_t})'$

And let $\mathbf{z}_{\mathbf{t}}^{\mathbf{L}}$ be the set collecting the current and lagged values of $\mathbf{z}_{\mathbf{t}}$

-
$$\mathbf{z}_{\mathbf{t}}^{\mathbf{L}} = (\mathbf{z}_{\mathbf{t}}, \mathbf{z}_{\mathbf{t-1}}, ..., \mathbf{z}_{\mathbf{t}-(\mathbf{L-1})})'$$

I suppose that inflation, $y_t \in \mathbb{R}$, evolves nonlinearly wrt $\mathbf{z}_t^{\mathbf{L}}$ through a function G, such that

 $y_{t+h} = G(\mathbf{z}_{\mathbf{t}}^{\mathbf{L}}; \Theta_h) + \varepsilon_{t+h}$

G is a *neural network*

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 \boldsymbol{G} is a neural network

Fitting the unknown function $G : \mathbf{z}_{\mathbf{t}}^{\mathbf{L}} \to y_{t+h}$ to the data corresponds to estimating Θ_h given a network architecture, \mathcal{A}_G , by minimizing

$$\mathcal{L} = \frac{1}{T} \sum_{t=1}^{T} \left(y_{t+h} - G(\mathbf{z_t^L}; \Theta_h) \right)^2$$

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$$\mathcal{L} = \frac{1}{T} \sum_{t=1}^{T} \left(y_{t+h} - G(\mathbf{z_t^L}; \Theta_h) \right)^2$$

- \mathcal{A}_G : neural net model & tunning parameters (hyperparameters)
- Universal approximation theorem (Cybenko, 1989): simple neural net model can approximate any continuous function up to an arbitrary degree of accuracy

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The Models

- 1. Feed forward (FF) model [multilayer perceptron] (FF-pool) $\mathbf{z_t} = \mathbf{x_t}$ (FF-cpi) $\mathbf{z_t} = \mathbf{y_t}$
- 2. Long-short term memory (LSTM) model [*recurrent* neural net] (LSTM-pool) $\mathbf{z_t} = \mathbf{x_t}$ (LSTM-all) $\mathbf{z_t} = (\mathbf{x_t}, \mathbf{y_t})'$
- 3. FF-LSTM model $\mathbf{z_t} = (\mathbf{x_t}, \mathbf{y_t})'$

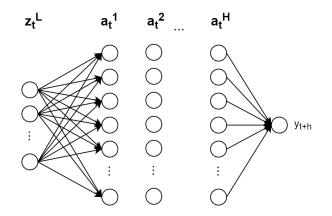
The Models

1. The Feed forward (FF) model

2. The LSTM model

3. The FF-LSTM model

The feed forward model



▶ FF equations

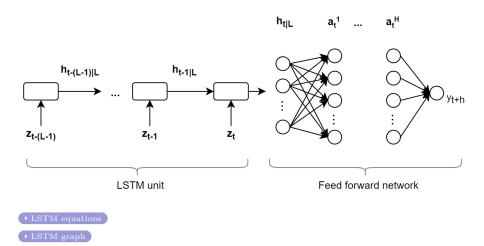
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Predicting Inflation with Neural Nets

The Models

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The LSTM model



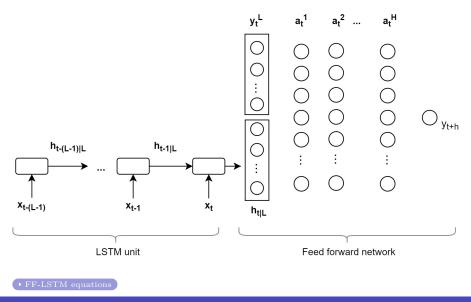
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The FF-LSTM model



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Data

- FRED-MD data base, downloaded in November, 2019 (128 series, 730 observations)
- Data set $\mathbf{y_t}$ (M = 10)
 - ▶ CPI: all items, apparel, transportation, medical care, commodities, durables, services, all items less food, all items less shelter, all items less medical care
- Data set $\mathbf{x_t}$ (N = 118)
 - Output&Income, Labour market, Housing, Consumption, Money&Credit, Interest&ER, Prices, Stock market

Optimal tuning parameters

	lags	nodes	layers	factors	# par.
FF-cpi	24	128	4	n/a	80K
FF-pool	48	128	3	n/a	$760 \mathrm{K}$
LSTM-pool	48	128	4	2	50K
LSTM-all	48	128	4	2	50K
FF-LSTM	24, 48	128	4	2	80K

Tuning parameters

• Variable selection

Out-of-sample performance

Table: Loss ratios wrt the AR(1) model over 2006M08-2019M10

		Horizon (months)					
Model	Data	1	3	6	12	24	
RMSE							
UCSV	CPI	1.13	1.05	1.03	1.02	1.00	
FADL	Pool	1.05	1.09	1.08	1.01	1.00	
FF-cpi	CPI	1.07	1.01	1.01	0.98	0.91	
FF-pool	Pool	1.09	0.92	0.90	0.94	0.99	
LSTM-pool	Pool	1.00	0.93	1.03	0.93	0.92	
LSTM-all	All	0.98	0.94	1.04	0.92	0.91	
FF-LSTM	All	1.06	0.99	0.99	0.97	0.89	

Horizon (months)

 \blacktriangleright Initial values



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RMSE over time

Fluctuation test (Giacomini and Rossi (2010))

▶ Test for equal forecast accuracy robust to instability

RMSE over time

Fluctuation test (Giacomini and Rossi (2010))

▶ Test for equal forecast accuracy robust to instability

In this application

- ► Statistic above the critical value implies the candidate model is superior to the benchmark for a specific time window
- ▶ Rolling window of m = 48 observations across the out-of-sample

RMSE over time (cont'd)



(a) Horizon 3

(b) Horizon 6



(c) Horizon 12



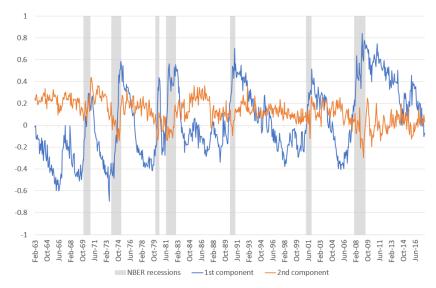
(d) Horizon 24



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Predicting Inflation with Neural Nets

Common components (FF-LSTM, horizon 24)



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Conclusions

- Proposes to forecast inflation using **recurrent** neural networks
 - Highly nonlinear
 - Suitable for time series analysis
- Relevance of macroeconomic predictors
- (Recurrent) Neural networks are promising to forecast inflation at **medium-long** horizons

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The feed forward model

$$G(\mathbf{z_t^L}; \Theta_h) = g_{FF} \Big(\mathbf{z_t^L}; \theta_h \Big)$$

and

$$\begin{split} g_{FF}(\mathbf{z}_{\mathbf{t}}^{\mathbf{L}};\theta_{h}) &= \mathbf{W}_{\mathbf{H}+1}\mathbf{a}_{\mathbf{t}}^{\mathbf{H}} + b_{H+1} \\ \mathbf{a}_{\mathbf{t}}^{\mathbf{i}} &= ReLu(\mathbf{W}_{\mathbf{i}}\mathbf{a}_{\mathbf{t}}^{\mathbf{i}-1} + \mathbf{b}_{\mathbf{i}}), \quad i = 1, 2, ..., H \\ \mathbf{a}_{\mathbf{t}}^{\mathbf{0}} &= \mathbf{z}_{\mathbf{t}}^{\mathbf{L}} \end{split}$$

where

$$\begin{split} \mathbf{a}_{\mathbf{t}}^{\mathbf{i}} \colon n \times 1 \text{ hidden layer vectors} \\ \theta_{h} &= (\{\mathbf{W}_{\mathbf{i}}\}_{i=1}^{H}, \{\mathbf{b}_{\mathbf{i}}\}_{i=1}^{H})' \text{: model parameters} \\ ReLu : \mathbb{R} \to \mathbb{R} \text{: rectified linear unit function } f(z) = max\{0, z\} \end{split}$$

$$\mathcal{A}_G = \{ G(\mathbf{z}_{\mathbf{t}}^{\mathbf{L}}; \Theta_h), L, n, H \}$$

The LSTM model $G(\mathbf{z}_{\mathbf{t}}^{\mathbf{L}}; \Theta_h) = g_{FF} \left(\mathbf{h}_{\mathbf{t}|\mathbf{L}}(\mathbf{z}_{\mathbf{t}}; \phi_h); \theta_h \right)$

where $t|L \equiv t|t, t - 1, ..., t - (L - 1)$



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The LSTM model $G(\mathbf{z}_{t}^{L}; \Theta_{h}) = g_{FF} \left(\mathbf{h}_{t|L}(\mathbf{z}_{t}; \phi_{h}); \theta_{h} \right)$ $\mathbf{f}_{t|L} = sigmoid(\mathbf{W}_{f}'\mathbf{z}_{t} + \mathbf{U}_{f}\mathbf{h}_{t-1|L} + \mathbf{b}_{f})$ $\mathbf{i}_{t|L} = sigmoid(\mathbf{W}_{i}'\mathbf{z}_{t} + \mathbf{U}_{i}\mathbf{h}_{t-1|L} + \mathbf{b}_{i})$ $\mathbf{o}_{t|L} = sigmoid(\mathbf{W}_{o}'\mathbf{z}_{t} + \mathbf{U}_{o}\mathbf{h}_{t-1|L} + \mathbf{b}_{o})$

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where $t|L \equiv t|t, t-1, ..., t - (L-1)$ $\mathbf{f}, \mathbf{i}, \mathbf{o}, \mathbf{c}, \mathbf{h} \in \mathbb{R}^{s \times 1}$



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where

$$t|L \equiv t|t, t - 1, ..., t - (L - 1)$$

$$\mathbf{f}, \mathbf{i}, \mathbf{o}, \mathbf{c}, \mathbf{h} \in \mathbb{R}^{s \times 1}$$

$$\Theta_h = (\phi_h, \theta_h)', \text{ with}$$

$$\phi_h = (\mathbf{W}_{(\mathbf{j})}, \mathbf{U}_{(\mathbf{j})}, \mathbf{b}_{(\mathbf{j})})', \ j = f, i, o, c$$

$$\theta_h = (\{\mathbf{W}_i\}_{i=1}^H, \{\mathbf{b}_i\}_{i=1}^H)', \text{ given } n \text{ and } H$$

∢Go Back

The LSTM model $G(\mathbf{z}_{t}^{L}; \Theta_{h}) = g_{FF} \left(\mathbf{h}_{t|L}(\mathbf{z}_{t}; \phi_{h}); \theta_{h} \right)$ $\mathbf{f}_{t|L} = sigmoid(\mathbf{W}_{f}'\mathbf{z}_{t} + \mathbf{U}_{f}\mathbf{h}_{t-1|L} + \mathbf{b}_{f})$ $\mathbf{i}_{t|L} = sigmoid(\mathbf{W}_{o}'\mathbf{z}_{t} + \mathbf{U}_{o}\mathbf{h}_{t-1|L} + \mathbf{b}_{i})$ $\mathbf{o}_{t|L} = sigmoid(\mathbf{W}_{o}'\mathbf{z}_{t} + \mathbf{U}_{o}\mathbf{h}_{t-1|L} + \mathbf{b}_{o})$ $\mathbf{c}_{t|L} = \mathbf{f}_{t|L} \odot \mathbf{c}_{t-1|L} + \mathbf{i}_{t|L} \odot tanh(\mathbf{W}_{c}'\mathbf{z}_{t} + \mathbf{U}_{c}\mathbf{h}_{t-1|L} + \mathbf{b}_{c})$ $\mathbf{h}_{t|L} = \mathbf{o}_{t|L} \odot tanh(\mathbf{c}_{t|L})$ $\mathbf{h}_{0} = \mathbf{0}, \quad \mathbf{c}_{0} = \mathbf{0}$

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$$\mathcal{A}_G = \{G(\mathbf{z}_{\mathbf{i}}^{\mathbf{L}}; \Theta_h), s, L, n, H\}$$



The FF-LSTM model

$$G(\mathbf{z}_{\mathbf{t}}^{\mathbf{L}};\Theta_{h}) = g_{FF} \Big((\mathbf{h}_{\mathbf{t}|\mathbf{L}}(\mathbf{z}_{\mathbf{t}};\phi_{h}), \mathbf{z}_{\mathbf{t}}^{\mathbf{L}})';\theta_{h} \Big)$$

where

$$t|L \equiv t|t, t-1, ..., t - (L-1)$$

$$\Theta_h = (\phi_h, \theta_h)',$$

$$\mathcal{A}_G = \{G(\mathbf{z_t^L}; \Theta_h), s, L, n, H\}$$

 g_{FF} receives the input vector $(\mathbf{h_t}_{|\mathbf{L}}(\cdot), \mathbf{z_t^L})' \in \mathbb{R}^{(s+ML) \times 1}$



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Sensitivity to initial values (I)

- The predictions at each point in time are averages over 1400 predictions with distinct initial values
- Non-convexity increases the sensitivity of the algorithm to initial values

Counterfactual exercise

- Compute the performance of all 1400 prediction series over the out-of-sample set
- Compare the series with minimum error out-of-sample with the average prediction series

Sensitivity to initial values (II)

Model	Horizons (months)				
	1	3	6	12	24
RMSE					
FF-cpi	0.96	0.97	0.95	0.98	0.97
FF-pool	0.96	0.96	0.95	0.93	0.89
LSTM-pool	0.97	0.93	0.89	0.96	0.93
LSTM-all	0.91	0.99	0.86	0.99	0.96
FF-LSTM	0.96	0.97	0.97	0.96	0.94

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Variable selection

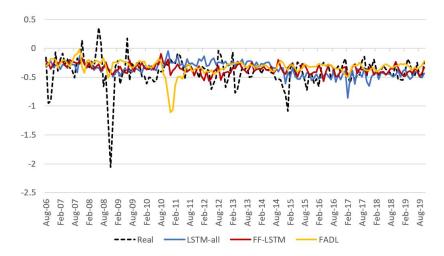


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A word on identification

- No guarantee of global optimum
 - Neural networks focus on good prediction accuracy on unseen data, ultimately an empirical question
 - Multiple equilibria and/or flat regions: intrinsic symmetry, mutual dependence of weights
- Non-convexity increases the sensitivity of the learning algorithm to initial values
 - Zero-mean uniform distribution
 - Empirical solution: average out the predictions of large number of repeats
- No identification explains the use of cross-validation as model selection (no probabilistic assumptions)

Predictions at the two-year ahead horizon



◀ Go Back

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The LSTM

